Milestone 2 report:

# Subsystem details:

|  |  |
| --- | --- |
| The subsystems are as follows: | |
|  | Robot simulator block, |
|  | Encoder block, |
|  | Motor block, |
|  | Line sensor block, |
|  | Ultrasonic sensor block, |
|  | *Another block* |

# Distance and Angle Control Algorithm:

# Line Following Algorithm:

# Object Detection Algorithm:

# Localisation Algorithm: